

Problem Set 2

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1. **Robustness of NC1.**

For a function $f : \{0, 1\}^n \rightarrow \{0, 1\}$, prove the following are equivalent:

- f has a logarithmic depth circuit.
- f has a log depth formula.
- f has a polynomial sized formula.
- f has a log depth arithmetic formula: i.e., a formula with binary XOR (\mathbb{F}_2 -sum), and AND (\mathbb{F}_2 -multiplication) gates with some inputs being allowed to be the constant 1.

2. **Path vs co-Path.**

Give a logspace reduction for the following transform:

- Input:** (G, s, t) ; a directed graph G and two vertices s, t .
- Output:** (G', s', t') such that there is an $s' \rightarrow t'$ path in G' if and only if there is **no** $s \rightarrow t$ path in G .

If G has n vertices, how many vertices does G' have?

3. **Universal Algorithm.**

Give an explicit algorithm for Factoring such that the running time of this algorithm is polynomial if and only if Factoring can be solved in polynomial time.

4. **Hierarchy for Circuit Size.**

Show that $SIZE(n) \neq SIZE(n^2)$. (What is the tightest such hierarchy you can show?)

5. **Circuit Lower Bounds.**

Show that $EXPSPACE \not\subseteq SIZE(2^n/(100n))$.

6. **Formulas vs. Bounded width branching programs. (Optional/Extra Credit).**

This problem is "extra credit." It does not count towards your grade on the problem set. Solve it only to express your interest in the material. No collaboration/discussion allowed, and no looking up external websites/references. Writeup is as important as the idea behind your solution.

Show that a function $f : \{0, 1\}^n \rightarrow \{0, 1\}$ has a polynomial sized formula if and only if it has a width-8 branching programs of polynomial size.

For the harder direction, you may try to show the following: Given an arithmetic formula f of depth d , produce a "3-register straight-line program" of length 4^d that maps binary input registers (A, B, C) to $(A, B, C + f(x_1 \dots x_n) \cdot B)$, where each line of the straightline program is of the form $(A, B, C) \mapsto (A', B', C')$ with two of $\{A', B, C'\} = \{A, B, C\}$ (say $A' = A$ and $C' = C$) and the third one is a linear form, e.g. $B' = B + x_i \cdot A$.