## AM 106/206: Applied Algebra

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Lecture Notes 20

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## 1 Vector Spaces

• Reading: Gallian Ch. 19

• Today's main message: linear algebra (as in Math 21) can be done over any field, and most of the results you're familiar with from the case of  $\mathbb{R}$  or  $\mathbb{C}$  carry over.

• **Def:** A vector space over a field F is a set V with two operations  $+: V \times V \to V$  (vector addition) and  $\cdot: F \times V \to V$  (scalar multiplications) that satisfy the following properties:

1. V is an abelian group under +.

2.  $(ab) \cdot v = a \cdot (b \cdot v)$  for all  $a, b \in F$  and  $v \in V$ .

3.  $1 \cdot v = v$  for all  $v \in V$ .

4.  $a \cdot (v + w) = a \cdot v + a \cdot w$  for all  $a \in F$  and  $v, w \in V$ .

5.  $(a+b) \cdot v = a \cdot v + b \cdot v$  for all  $a, b \in F$  and  $v \in V$ .

• A vector space has more structure than an abelian group, but less structure than a ring (only multiplication by scalars, not multiplication of arbitrary pairs of elements of V).

• Examples and Nonexamples:

$$-V = F^n$$

$$-V=\mathbb{C}, F=\mathbb{R}$$

$$-V=\mathbb{Z}^n, F=\mathbb{Z}_2$$

$$-V = F[x]$$

$$-\ V = F[x]/\langle p(x)\rangle$$

-V = R for a ring R containing F.

- **Def:** Let V be a vector space over of F. Vectors  $v_1, \ldots, v_n \in V$  are linearly independent iff for every  $c_1, \ldots, c_n \in F$ , if  $c_1v_1 + \cdots + c_nv_n = 0$ , then  $c_1 = \cdots = c_n = 0$ . The vectors  $v_1, \ldots, v_n$  form a basis for V iff they are linearly independent and  $\mathrm{Span}(v_1, \ldots, v_n) = V$ , where  $\mathrm{Span}(v_1, \ldots, v_n) = \{c_1v_1 + \cdots + c_nv_n : c_1, \ldots, c_n \in F\}$ .
- Examples of bases:
  - $-(1,0,0,\cdots,0), (0,1,0,\ldots,0), \ldots, (0,0,0,\ldots,1)$  is a basis for  $F^n$  for every field F.
  - **Q**: Is (1,1,0), (1,0,1), (0,1,1) always a basis for  $F^3$ ?
  - Bases for other examples above?
- **Def:** The *dimension* of a vector space V over F is the size of the largest set of linearly independent vectors in V. (different than Gallian, but we'll show it to be equivalent)
  - A measure of "size" that makes sense even for infinite sets.
- **Prop:** Every finite-dimensional vector space has a basis consisting of  $\dim(V)$  vectors. Later we'll see that all bases have exactly  $\dim(V)$  vectors.

**Proof:** Let  $v_1, \ldots, v_k$  be the largest set of linearly independent vectors in V (so  $k = \dim(V)$ ). To show that this is a basis, we need to show that it spans V. Let w be any vector in V. Since  $v_1, \ldots, v_k, w$  has more than  $\dim(V)$  vectors, this set must be linearly dependent, i.e. there exists constants  $c_1, \ldots, c_k, d \in F$ , not all zero, such that  $c_1v_1 + \cdots + c_kv_k + dw = 0$ . The linear independence of  $v_1, \ldots, v_k$  implies that  $d \neq 0$ . Thus, we can write  $w = (c_1/d_1)v_1 + \cdots + (c_k/d_k)v_k$ . So every vector in V is in the span of  $v_1, \ldots, v_k$ .

- **Q:** What are the dimensions of the above examples?
- Corollaries:
  - If V is an n-dimensional vector space over a finite field F, then  $|V| = |F|^n$ .
  - If E is a finite field and F is a subfield of E, then  $|E| = |F|^n$  for some  $n \in \mathbb{N}$ . (Much stronger than Lagrange, which only says |F| divides |E|.)
  - if E is a finite field of characteristic p, then  $|E|=p^n$  for some  $n \in \mathbb{N}$ . (Shown on PS7 using Classification of Abelian Groups.)

## 2 Maps Between Vector Spaces

- **Def (vector-space homomorphisms):** Let V and W be two vector spaces over F. A function  $f: V \to W$  is a *linear map* iff for every  $x, y \in V$  and  $c \in F$ , we have
  - 1. f(x+y) = f(x) + f(y) (i.e. f is a group homomorphism), and
  - 2. f(cx) = cf(x).

f is an isomorphism if f is also a bijection. If there is an isomorphism between V and W, we say that they are isomorphic and write  $V \cong W$ .

• **Prop:** Every *n*-dimensional vector space V over F is isomorphic to  $F^n$ .

**Proof:** Let  $v_1, \ldots, v_n$  be a basis for V.

Then an isomorphism from  $F^n$  to V is given by:

- Matrices: A linear map  $f: F^n \to F^m$  can be described uniquely by an  $m \times n$  matrix M with entries from F.
  - $-M_{ij}=f(e_j)_i$ , where  $e_j=(000\cdots 010\cdots 00)$  has a 1 in the j'th position.
  - For  $v=(v_1,\ldots,v_n)\in F^n$ ,  $f(v)_i=f(\sum_j v_je_j)_i=\sum_j v_jf(e_j)_i=\sum_i M_{ij}v_j=(Mv)_i$ , where Mv is matrix-vector product.
  - Matrix multiplication  $\leftrightarrow$  composition of linear maps.
  - If n = m, then f is an isomorphism  $\Leftrightarrow \det(M) \neq 0$ .
  - Solving Mv = w for v (when given M and  $w \in F^m$ ) is equivalent to solving a linear system with m variables and n unknowns.
- **Example:**  $f: \mathbb{Z}_3^3 \to \mathbb{Z}_2^3$  given by  $f(v_1, v_2, v_3) = (v_1 + 2v_2, 2v_1 + v_3)$ .
- Thm: If  $f: V \to W$  is a linear map, then  $\dim(\ker(f)) + \dim(\operatorname{im}(f)) = \dim(V)$ .

**Proof:** omitted.

- When F finite, this says  $|V| = |F|^{\dim(V)} = |F|^{\dim(\ker(f))} \cdot |F|^{\dim(\operatorname{im}(f))} = |\ker(f)| \cdot |\operatorname{im}(f)|$ , just like for group homomorphisms!
- Corollaries:
  - $-F^n \ncong F^m \text{ if } m \neq n.$
  - All bases of a vector space have the same size.
  - A homogenous linear system Mv = 0 for a given  $m \times n$  matrix M always has a nonzero solution v if n > m (more variables than unknowns).
- Computational issues: For  $n \times n$  matrices over F,
  - Matrix multiplication can be done with  $O(n^3)$  operations in F using the standard algorithm.
  - The determinant and inverse, and solving a linear system Mv = w can be done using  $O(n^3)$  operations in F using Gaussian elimination. (For infinite fields, need to worry about the size of the numbers, or accuracy if doing approximate arithmetic. No such problem in finite fields.)

– Asymptotically fastest known algorithms run in time  $O(n^{2.376})$ . Whether time  $O(n^2)$  is possible is a long-standing open problem.

## 3 Application to Extension Fields

- Reading: parts of Gallian Ch. 21
- **Def:** E is an extension field of F is F is a subfield of E. The degree of E over F is the dimension of E as a vector space over F, and is denoted [E:F]. E is a finite extension if [E:F] is finite.
- Examples:

$$- [\mathbb{C} : \mathbb{R}] =$$

$$- [F[x]/\langle p(x)\rangle : F] =$$

$$- [F(\alpha) : F] =$$

- Thm 21.5: If K is a finite extension of E, and E is a finite extension of F, then [K:F] = [K:E][E:F].
- **Example:** The splitting field of  $x^8 1$  over  $\mathbb{Q}$ , i.e.  $\mathbb{Q}(\omega) = \mathbb{Q}(i)(\omega)$ , where  $\omega = e^{2\pi i/8}$ .
- Proof:

• Corollary: If E is a finite extension of F and  $\alpha \in E$ , then  $\alpha$  is algebraic over F and its minimal polynomial has degree dividing [E:F].