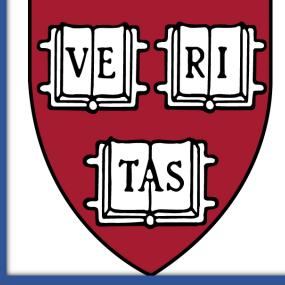
Personalized HeartSteps: A Reinforcement Learning Algorithm for Optimizing Physical Activity

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HEARTSTEPS STUDY

- HeartSteps is an ongoing, real-life physical activity clinical trial for improving the physical activity of individuals with blood pressure in the stage 1 hypertension range.
- Participants are provided a Fitbit tracker and a mobile phone application on the phone designed to help them improve their physical activity.
- One of the interventions is a contextually tailored physical activity suggestion that may be delivered at any of the five user-specified times during each day, corresponding to the user's morning commute, mid-day, midafternoon, evening commute, and postdinner times.

CHALLENGES TO APPLYING RL IN MOBILE HEALTH

The RL algorithm should learn quickly and accommodate noisy data.

Most online RL algorithms require the agent to interact many times with the environment prior to performing well. This is impractical in mobile health applications as users can lose interest and disengage quickly.

Proposal: Use a low-dimensional linear model with an informative prior

PERSONALIZED HEARTSTEPS

A low-dimensional linear model for immediate treatment effect

 $r(s, 1) - r(s, 0) = f(s)^{\mathsf{T}}\beta$

A *working* model for the baseline reward

 $r(s,0) \approx g(s)^{\mathsf{T}} \alpha$

The posterior distribution of β is found by an action-centered linear model of reward

 $R_{t+1} = g(S_t)^{\mathsf{T}} \alpha_0 + \pi_t f(S_t)^{\mathsf{T}} \alpha_1$

The content of the suggestion is designed to encourage activity in the current context

RL FRAMEWORK

$\{S_1, A_1, R_2, S_2, A_2, R_3, \dots, S_t, A_t, R_{t+1}\}$

- Decision time t: 5 times/day, 90-day study
- Action A_t : binary send vs do nothing
- States S_t: location, prior 30-minute step count, daily step count, the temperature, app usage...
- Reward R_{t+1} : number of steps taken in the 30 minutes after decision time
- **Goal**: at each decision time, determine whether or to send the walking suggestion message based on user's context, with the goal to maximize the total step counts

The RL algorithm should accommodate some model mis-specification and non-stationarity. Due to unobserved aspects of the current context (engagement or burden), observed human behavior is complex to model and often exhibits non-stationarity over longer periods of time

Proposal: Use action-centering in modeling the reward

The RL algorithm must adjust for longer term effects of current actions

In mobile health, interventions often tend to have positive effect on the immediate reward, but likely produce negative impact on the future rewards due to user habituation and/or burden

Proposal: Construct a low-variance proxy of future rewards based on a dosage variable

The RL algorithm should select actions so that after the study is over, secondary data analyses are feasible.

An interdisciplinary team is often required to design the intervention and to conduct the clinical trial. Multiple stakeholders needs to analyze the resulting data in a large variety of ways, e.g., off-policy learning and causal inference

Proposal: the actions are selected randomly with a bounded probability $+ (A_t - \pi_t)f(S_t)^{\mathsf{T}}\beta + \epsilon_t$

where α_0 , α_1 , β follow a normal prior

• To capture the delayed effect of action, we construct a proxy of future rewards based on a dosage variable X_t ,

$$X_{t+1} = \lambda X_t + A_t$$

• The proxy value function $\widehat{H}(x, a)$ is formed based on an approximate MDP for the states $S_t = (X_t, Z_t)$, where $\{Z_t\}$ are i.i.d. with some estimated distribution *F* :

$$\widehat{H}(x,a) \approx E_{\pi^*} [R_{t+2} + \gamma R_{t+3} + \gamma^2 R_{t+4}]$$

$$+ \cdots \mid X_t = x, A_t = a]$$

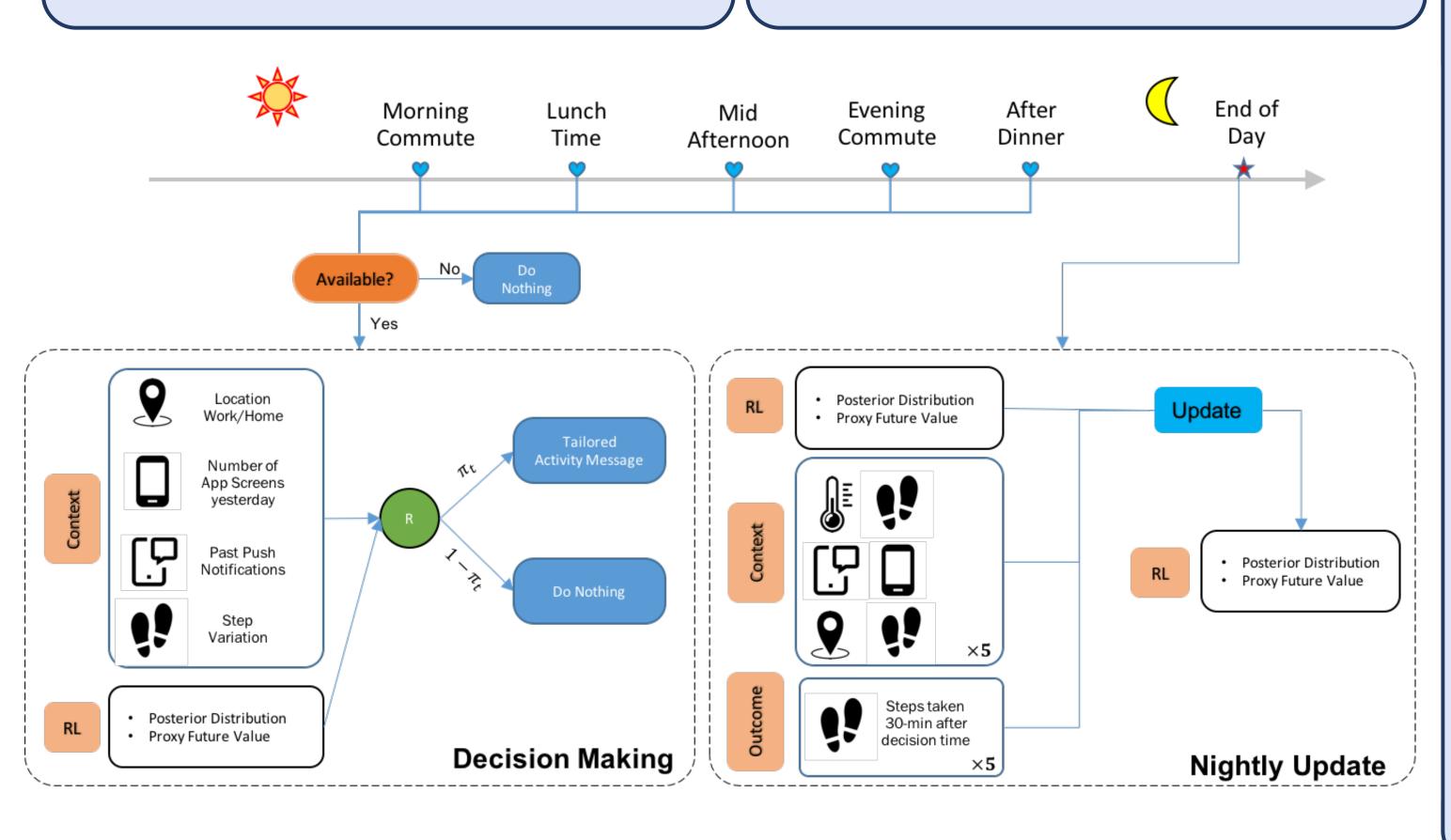
• The action A_t is selected stochastically with probability $\pi_t: \hat{\beta} \sim N(\mu_\beta, \Sigma_\beta)$

 $\pi_t = \Pr(f(S_t)^{\top} \widetilde{\beta} > \gamma \widehat{H}(X_t, 0) - \gamma \widehat{H}(X_t, 1))$

IMPLEMENTATION

- A 42-day pilot study (HS 1.0) is conducted with 37 participants
- The feature vectors, as well as the prior distribution of parameters are selected based





on GEE analysis of pilot study.

- The tuning parameters are chosen based on a generative model built from HS 1.0.
- Cross-validation is performed to demonstrate the use of proxy value is able to pick up the delayed effect of treatment – compare with standard Thompson sampling Bandit

